# Q4X Stainless Steel Laser Sensor with Dual Discrete Outputs and IO-Link

**Instruction Manual** 





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## 1 Product Description

Class 1 laser CMOS sensor with dual outputs and IO-Link. Patent pending.

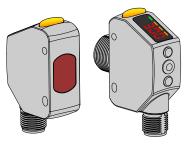


Figure 1. Flush Mount (Left) and Threaded Barrel (Right) Models

- The ultimate problem solver: reduce sensor inventory with a reliable, durable sensor that solves the most challenging applications
- Solves difficult distance-based applications regardless of target surface reflectivity, including black foam on black plastic, black rubber in front of metal, transparent objects, multicolor packaging, and targets of all colors
- Robust housing rated to IP69K with FDA-grade stainless steel resists mechanical impact, over tightening and extreme vibration
- Bright output indicator and real time distance feedback provide easy setup and troubleshooting for reduced installation costs
- Dual channels and IO-Link

For illustration purposes, the threaded barrel model Q4X images are used throughout this document.



WARNING: Not To Be Used for Personnel Protection

Never use this device as a sensing device for personnel protection. Doing so could lead to serious injury or death. This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A sensor failure or malfunction can cause either an energized or de-energized sensor output condition.

### 1.1 Models

Model		Sensing Range	Channel 1	Channel 2	Connection
	Q4XTKLAF600-Q8	25 mm to 600 mm (0.98 in to 23.62 in)	IO-Link, Push/pull output i	PNP only output or input, or pulse frequency modulated output	Integral 4-pin M12/ Euro-style male quick disconnect (QD)
	Q4XTKLAF300-Q8	25 mm to 300 mm (0.98 in to 11.81 in)			
	Q4XTKLAF100-Q8	25 mm to 100 mm (0.98 in to 3.94 in)			
	Q4XFKLAF610-Q8	35 mm to 610 mm (1.38 in to 24.02 in)	IO-Link, Push/pull output	PNP only output or input, or pulse frequency modulated output	Integral 4-pin M12/ Euro-style male quick disconnect (QD)
	Q4XFKLAF310-Q8	35 mm to 310 mm (1.38 in to 12.20 in)			
	Q4XFKLAF110-Q8	35 mm to 110 mm (1.38 in to 4.33 in)			

#### 1.2 Overview

The Q4X sensor with dual discrete outputs and IO-Link is a Class 1 laser CMOS sensor with an IO-Link and multifunction output. The normal sensor state is Run mode. From Run mode, the switch point value and channel selection can be changed and the selected TEACH method can be performed. The secondary sensor state is Setup mode. From Setup mode, the TEACH mode can be selected, all standard operating parameters can be adjusted, and a factory reset can be done.

### 1.3 Features



Figure 2. Sensor Features

- 1. Output Indicator (Amber)
- 2. Display
- 3. Buttons

### 1.3.1 Display and Indicators

The display is a 4-digit, 7-segment LED. The main screen is the Run mode screen.

For 2-pt, BGS, FGS, and DYN TEACH modes, the display shows the current distance to the target in millimeters. For dual TEACH mode, the display shows the percentage matched to the taught reference surface. A display value of percentage matched to the taught reference surface. A display value of percentage matched to the taught reference surface. A display value of percentage matched to the taught reference surface. A display value of percentage matched to the taught reference surface. A display value of percentage matched to the taught reference surface. A display value of percentage matched to the taught reference surface. A display value of percentage matched to the taught reference surface. A display value of percentage matched to the taught reference surface. A display value of percentage matched to the taught reference surface. A display value of percentage matched to the taught reference surface.



Figure 3. Display in Run Mode

- 1. Stability Indicator (STB—Green)
- 2. Active TEACH Indicators
  - DYN—Dynamic (Amber)
  - FGS—Foreground Suppression (Amber)
  - BGS—Background Suppression (Amber)



Note: The indicators represent the currently selected channel. However, if Output 2 is set to something other than LO, DO, or Complementary, then the indicators represent the Channel 1 status.

#### **Output Indicator**

- · On—Output is on
- · Off—Output is off

#### Active TEACH Indicators (DYN, FGS, and BGS)

- DYN, FGS, and BGS all off—Two-point TEACH mode selected (default)
- DYN on—Dynamic TEACH mode selected
- FGS on—Foreground suppression TEACH mode selected
- BGS on—Background suppression TEACH mode selected
- DYN, FGS, and BGS all on—Dual TEACH mode selected

#### Stability Indicator (STB)

- On—Stable signal within the specified sensing range
- Flashing—Marginal signal, the target is outside the limits of the specified sensing range, or a multiple peak condition exists
- Off—No target detected within the specified sensing range

#### 1.3.2 Buttons

Use the sensor buttons (SELECT)(TEACH), (+)(CH1/CH2), and (-)(MODE) to program the sensor.



#### (SELECT)(TEACH)

- Press to select menu items in Setup mode
- Press and hold for longer than 2 seconds to start the currently selected TEACH mode (the default is twopoint TEACH)

#### (-)(MODE)

- Press to navigate the sensor menu in Setup mode
- Press to change setting values; press and hold to decrease numeric values
- Press and hold for longer than 2 seconds to enter Setup mode

#### (+)(CH1/CH2)

- Press to navigate the sensor menu in Setup mode
- Press to change setting values; press and hold to increase numeric values
- Press and hold for longer than 2 seconds to switch between Channel 1 and Channel 2



Note: When navigating the menu, the menu items loop.

### 1.4 Laser Description and Safety Information



CAUTION: Use of controls or adjustments or performance of procedures other than those **specified** herein may result in hazardous radiation exposure. Do not attempt to disassemble this sensor for repair. A defective unit must be returned to the manufacturer.

#### Class 1 Lasers

Class 1 lasers are lasers that are safe under reasonably foreseeable conditions of operation, including the use of optical instruments for intrabeam viewing.

COMPLIES WITH 21 CFR 1040.10 AND 1040.11
EXCEPT FOR DEVIATIONS PURSUANT TO
LASER NOTICE No. 50, DATED JUNE 24, 2007.
BANNER ENGINEERING CORP.
9714 10TH AVBURE NORTH
MINNEAPOLIS, MN 55441

COMPLIES WITH IEC 60825-1:2007

Laser wavelength: 655 nm Output: < 0.20 mW Pulse Duration: 7 µs to 2 ms

## 2 Installation

## 2.1 Install the Safety Label

The safety label must be installed on Q4X sensors that are used in the United States.



Note: Position the label on the cable in a location that has minimal chemical exposure.

- 1. Remove the protective cover from the adhesive on the label.
- 2. Wrap the label around the Q4X cable, as shown.
- 3. Press the two halves of the label together.

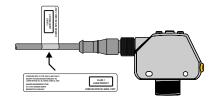


Figure 4. Safety Label Installation

### 2.2 Sensor Orientation

Optimize detection reliability and minimum object separation performance with correct sensor-to-target orientation. To ensure reliable detection, orient the sensor as shown in relation to the target to be detected.

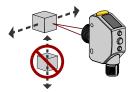


Figure 5. Optimal Orientation of Target to Sensor

See the following figures for examples of correct and incorrect sensor-to-target orientation as certain placements may pose problems for sensing some targets. The Q4X can be used in the less preferred orientation and provide reliable detection performance; refer to the *Performance Curves* for the minimum object separation distance required for each case.

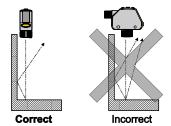


Figure 6. Orientation by a wall

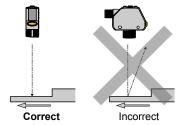


Figure 8. Orientation for a height difference

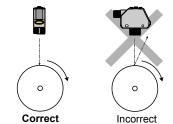


Figure 7. Orientation for a turning object

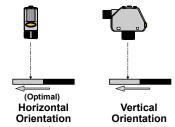


Figure 9. Orientation for a color or luster difference

#### 2.3 Mount the Sensor

6

- 1. If a bracket is needed, mount the sensor onto the bracket.
- Mount the sensor (or the sensor and the bracket) to the machine or equipment at the desired location. Do not tighten the mounting screws at this time.

- 3. Check the sensor alignment.
- 4. Tighten the mounting screws to secure the sensor (or the sensor and the bracket) in the aligned position.

### 2.4 Wiring Diagram

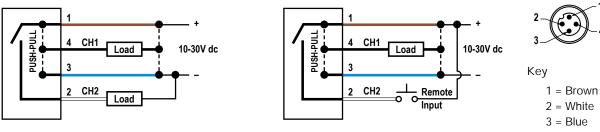


Figure 10. Channel 2 as PNP discrete or PFM output

Figure 11. Channel 2 as remote input

4 = Black



Note: Open lead wires must be connected to a terminal block.



Note: The Channel 2 wire function is user-selectable. The default for the wire is PNP output. See the Instruction Manual for details regarding use as remote input or PFM output.

### 2.5 Cleaning and Maintenance

Handle the sensor with care during installation and operation. Sensor windows soiled by fingerprints, dust, water, oil, etc. may create stray light that may degrade the peak performance of the sensor. Blow the window clear using filtered, compressed air, then clean as necessary using water and a lint-free cloth.

## 3 Sensor Programming

Program the sensor using the buttons on the sensor or the remote input (limited programming options).

In addition to programming the sensor, use the remote input to disable the buttons for security, preventing unauthorized or accidental programming changes. See *Locking and Unlocking the Sensor Buttons* on page 18 for more information.

### 3.1 Channel 1 and Channel 2 (CH1/CH2)

Press CH1/CH2 button to switch between Channel 1 and Channel 2. Within each channel there are options **specific** to that channel. For settings that are common to both channels, the menus are only available in Channel 1. The default is Channel 1.

To switch between Channel 1 and Channel 2:

- 1. Press and hold CH1/CH2 for longer than 2 seconds. The current selection displays.
- 2. Press CH1/CH2 again. The new selection flashes slowly.
- 3. Press SELECT to change the Channel and return to Run mode.



Note: If neither SELECT nor CH1/CH2 are pressed after step 2, the new selection flashes slowly for a few seconds, then flashes quickly and the sensor automatically changes the Channel and returns to Run mode.

### 3.2 Setup Mode

Access Setup mode and the sensor menu from Run mode by pressing and holding MODE for longer than 2 seconds. Use  $^igoplus$  and

to navigate through the menu. Press SELECT to select a menu option and access the submenus. Use through the submenus. Press SELECT to select a submenu option and return to the top menu, or press and hold SELECT for longer than 2 seconds to select a submenu option and return immediately to Run mode.

To exit Setup mode and return to Run mode, navigate to and press SELECT.



Note: The number that follows a menu option, for example before, indicates the channel that is selected. For menu items without a number (excluding submenu items), these menu options are only available from Channel 1 and the settings apply to both channels.

#### Channel 1 Top Menu Sub Menu **↑** • + **+** Output CH1 - Lo ✓ Light Operate ( ✓ default setting) <u>օ</u>սե ( do Dark Operate Teach Selection CH1 beh l 89n 865 Dynamic Teach Foreground Suppression Background Suppression duRL Dual Mode Adaptive Tracking CH1 \* on: Adaptive Tracking on off: Adaptive Tracking off High-Speed Adaptive Tracking on \* Adaptive Tracking menu is available when Teach CH1 is set to Dual Mode Window Size CH1 \*\* 32 + 2 75 0.2 to x, where x depends on measuring span: 75 for 100/110 mm models 275 for 300/310 mm model <u>ವಿಗಡೆ</u> ! 275 for 300/310 mm models 575 for 600/610 mm models \*\* Window Size menu is available when Teach CH1 is set to FGS Response Speed CH1 & CH2 100/110 & 300/310 mm Model Response Speeds 600/610 mm Model Response Speeds set Response Speed to 2 ms 1.5 3 set Response Speed to 1.5 ms set Response Speed to 3 ms set Response Speed to 5 ms ✓ set Response Speed to 10 ms set Response Speed to 15 ms set Response Speed to 25 ms ✓ set Response Speed to 25 ms set Response Speed to 50 ms set Response Speed to 50 ms Gain and Sensitivity CH1 & CH2 CA on H ICH v high excess gain mode 56 standard excess gain with increased noise immunity Output Timing Delays CH1 8L9 ( - ₫ৣৣਜ਼ৢਜ਼ on: enable on and/or off delay (set value in Delay Timer menu) - 15ho 1 Shot, fixed output pulse duration totalizer Delay Timer CH1 \*\*\* Available when ms to 30.0 sec range, set Delay Timer value (seconds have decimal) dL31 set to on oFd i \*\*\* Menu not present when #LB! is set to #FF did set to East (and and aFd default to 0, dt defaults to 1 or 10 depending on response speed setting) d≿ / available when aly set to bable Select Zero Reference Location CH1 & CH2 mean: set zero displayed value to end of 18 mm barrel 28ra - FRA far: set zero displayed value to maximum detection range Shift Zero Reference after Teach CH1 & CH2 SHFE SELECT OF on: move the zero point after each teach off: zero point is either at end of barrel or maximum detection range Offset CH1 \*\*\* ✓ Set Value: -75 to 75 for 100/110 mm models -275 to 275 for 300/310 mm models SELECT --575 to 575 for 600/610 mm models \*\*\*\* Offset menu is available when Teach CH1 is set to FGS or BGS Display Read CH1 & CH2 d (5P — 1234 ✓ display on display on, inverted display off (enters short) display off (enters sleep mode after 60 seconds) 330 display off, inverted (enters sleep mode after 60 seconds) **Exit Setup** End End end: exit setup Reset to Factory Defaults CH1 & CH2 **H586** no: do not reset to factory defaults yes: reset to factory defaults

Figure 12. Sensor Menu Map—Channel 1

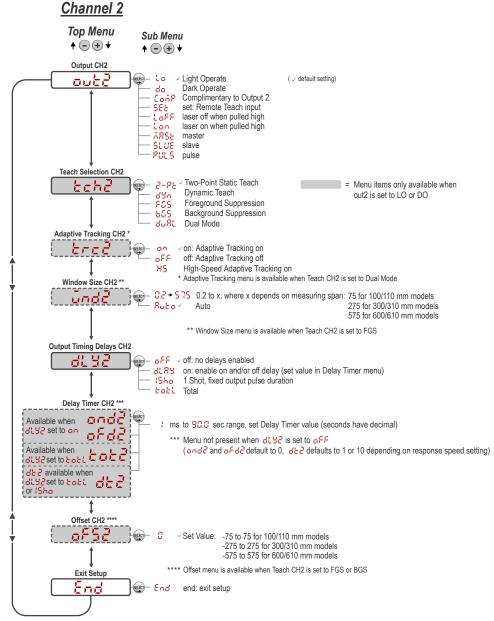


Figure 13. Sensor Menu Map—Channel 2

## 3.2.1 Output 🕶 🚼 💆



Note: The number that follows out on the display indicates which channel is selected.

The Output 1 menu is available in Channel 1. Use this menu to select light operate (LO) or dark operate (DO). The default output configuration is light operate. To switch between light operate and dark operate, select the desired menu option.

- Light operate
- □□ —Dark operate

The Output 2 menu is available in Channel 2. Use this menu to set the output configuration for Channel 2. The default is light operate.

- Light operate
- <sup>d</sup>□ —Dark operate

- Complementary to output 1
- 555 —Remote TEACH input
- Laser off when pulled high
- Laser on when pulled high
- Master sync line output for two-sensor cross-talk avoidance
- 54 115 —Slave sync line output for two-sensor cross-talk avoidance
- Pulse Frequency Modulation (PFM) output (see Pulse Frequency Modulation (PFM) Output on page 28)

To configure the sensor for master-slave operation, see Sync Master/Slave on page 28.

## 3.2.2 TEACH Mode teh! teh?

Use this menu to select the TEACH mode. The default is two-point TEACH. For Channel 2, this menu is available when the output is set to light operate or dark operate.



Note: The number that follows tch on the display indicates which channel is selected.

- Z-Pt —Two-point static background suppression
- Dynamic background suppression
- FC5 —One-point window (foreground suppression)
- bus —One-point background suppression
- Dual (intensity + distance) window

After the TEACH mode is selected, from Run mode, press and hold TEACH for longer than 2 seconds to start the TEACH mode and program the sensor. See *TEACH Procedures* on page 19 for additional information and remote input TEACH instructions.

## 3.2.3 Adaptive Tracking to ! to ?

Use these menus to set the adaptive tracking algorithm. This menu is available only if dual (intensity + distance) mode is selected. For Channel 2, the output must be set to light operate or dark operate.



Note: The number that follows trc on the display indicates which channel is selected.

- High-Speed Adaptive Tracking On
- —Adaptive Tracking On (default)
- Adaptive Tracking Off

## 3.2.4 Window Size ਪੂਰਰੀ ਂ ਪੂਰਰੀ

This menu is available only if one-point window (foreground suppression) mode is selected. The default selection is Auto, where the FGS window size is automatically calculated.

This menu can be used to manually set a window size. See the following table for the window size range:

Window Size	Models
0.1 mm to 75 mm	100 mm and 110 mm models
0.2 mm to 275 mm	300 mm and 310 mm models
0.2 mm to 575 mm	600 mm and 610 mm models

This setting is automatically applied during any subsequent teach operation. The window size value represents a +/- mm value, so the total window size is twice this value. For example, a window set of 10 mm gives a 20 mm window centered around the taught point. The window size can also be changed directly from Run mode after changing the setting to any value except Auto. For Channel 2, the output must be set to light operate or dark operate.

## 3.2.5 Response Speed 5 - 100/110/300/310 mm Models

Use this menu to select the response speed. The default is 10 milliseconds.

- —1.5 milliseconds
- ∃—3 milliseconds
- ☐ —10 milliseconds
- 25 milliseconds
- 50 milliseconds

Table 1: Tradeoffs

Response Speed	Response Speed in Sync Mode	Repeatability	Ambient Light Rejection	Excess Gain
1.5 ms	3 ms	500 μs	Disabled	
3 ms	6 ms	500 μs	Enabled	
10 ms	20 ms	2 ms	Enabled	See <i>Table 13</i> on page 31
25 ms	50 ms	5 ms	Enabled	
50 ms	100 ms	10 ms	Enabled	

## 3.2.6 Response Speed —600/610 mm Models

Use this menu to select the response speed. The default is 25 milliseconds.

- 5 —5 milliseconds
- 25 —15 milliseconds
- 25 milliseconds
- 50 milliseconds

Table 2: Tradeoffs

Response Speed	Response Speed in Sync Mode	Repeatability	Ambient Light Rejection	Excess Gain
2 ms	4 ms	800 µs	Disabled	
5 ms	10 ms	1600 µs	Enabled	
15 ms	30 ms	3 ms	Enabled	See <i>Table 14</i> on page 31
25 ms	50 ms	5 ms	Enabled	
50 ms	100 ms	10 ms	Enabled	

## 3.2.7 Gain and Sensitivity 58 in

Use this menu to set the excess gain mode. This menu is only available when a 10, 15, 25, or 50 millisecond response speed is selected. It is not available for 1.5, 2, 3, or 5 millisecond response speeds.

• High excess gain mode

Standard excess gain mode with increased noise immunity

## 3.2.8 Output Timing Delays

Use this menu to select the output timing delay to be set. On and off delay timers can be used together. The default is no delay. For Channel 2, this menu is available when the output is set to light operate or dark operate.



Note: The number that follows dLY on the display indicates which channel is selected.

- □FF —No delay
- Delay—enables the selection of on and off delay timers
- "5hp —One-shot—enables a one-shot, fixed output pulse duration
- Localizer—enables an output after a defined number of targets are counted

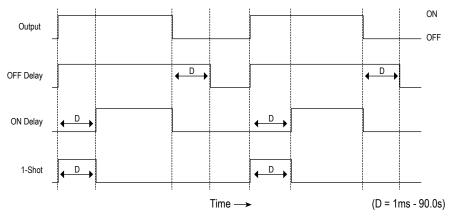


Figure 14. Output Timing Delays

When one of the timing delay options is chosen, the sensor returns to the Setup menu and additional options become available to set the parameter(s):

### al 84

- □□□□ —On delay
- □ F d Off delay

### 1555

• dt / dt - One-shot delay timer



Note: For the one-shot delay timer:

- LO = On pulse when a target is detected inside of the switch point(s)
- DO = On pulse when a target is detected outside of the switch point(s)

### F-6-1

- dt / dt d —Output duration
- tot //tot?—Number of counts before an output change

## Delay Timers and I and E afd afd afd at I dt E

Use these menus to set the delay timers. These menus are available only if an output timing delay is selected.

For and of the default is 0.

For the defaults are:

- 10 milliseconds for 10, 15, 25, and 50 millisecond response speeds
- 1 millisecond for 1.5, 2, 3, and 5 milliseconds response speeds

Use  $^{\scriptsize ullet}$  and  $^{\scriptsize ullet}$  to scroll through the values. Millisecond values do not include the decimal point; seconds values include the decimal point.

- 1 to 999 ms (when is selected, the 1 to 9 ms range is available for 1.5, 2, 3, and 5 ms response times)
- 1.0 to 90.0 s

## Totalizer

The totalizer function changes the output only after counting a designated number of targets. After selecting this function, d = 1 or d = 1 become available to define the output duration and d = 1 to define required number of counts before the output changes.

For bot and bot , the default is 1 count.

For d = 1 and d = 2, the default is 10 milliseconds. Use e = 2 and e = 2 to scroll through the values. Millisecond values do not include the decimal point; seconds values include the decimal point.

- 1.0 to 90.0 s

From Run mode, press SELECT to change the display to show the current totalizer count. Pressing SELECT again changes the display back to the measured distance.

The totalizer count automatically resets after re-teaching the switch point distance or turning the sensor off.

## 3.2.9 Zero Reference Location

Use this menu to select the zero reference location. The default is not available in dual (intensity + distance) mode.

- The front of the sensor; the measurement increases further from the sensor
- FR- —0 = maximum range; the measurement increases closer to the sensor

## 3.2.10 Shift the Zero Reference Location after a TEACH

Use this menu to select whether the sensor shifts the zero reference location based on the last TEACH process. The default is 0 = 0, 0 = 0 the front of the sensor or the maximum range. This menu is not available in dual (intensity + distance) mode.

- —Shift the zero reference location to one of the taught positions with each TEACH
- $\Box^{FF}$  —0 = the front of the sensor or the maximum range, depending on the  $\Box^{FF}$  setting

This figure illustrates three examples of how changes to the zero and shift settings affect what distance readout is shown on the display when in 2-pt TEACH mode. Changes to the zero setting affect the direction in which the distance increases.

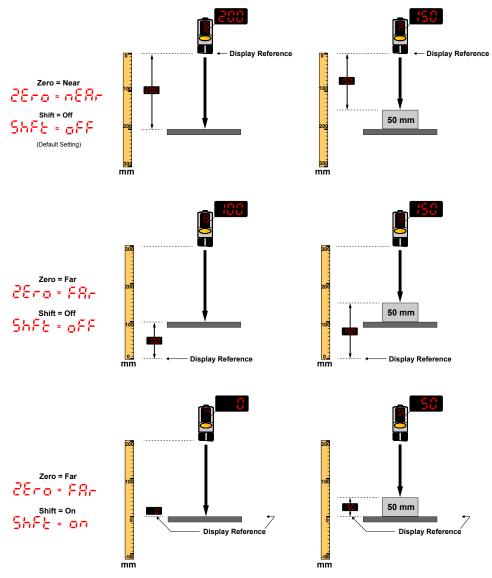


Figure 15. Example Zero and Shift settings

## 3.2.11 Offset **\$\opens\$** | \$\opens\$ **\$\opens\$** | \$\opens\$

Use this menu to set an offset from the taught surface. This menu is available only if one-point window (foreground suppression) mode or one-point background suppression mode is selected. For Channel 2, the output must be set to light operate or dark operate.



Note: The number that follows of S on the display indicates which channel is selected.

The offset is automatically calculated or manually defined as a consistently applied value. Auto is the default option. Use +/- to select a value. Values increase or decrease by 0.1 mm (100/110 mm models) or 0.2 mm (300/310/600/610 mm models).

For BGS mode, the default is Auto because the Q4X automatically selects where to position the switch point. For FGS mode, the default is 0 because the window is centered around the taught target.

A positive offset value always shifts the switch point location or the FGS window towards the sensor.

The taught surface must be inside of the defined sensing range. When the teach mode is set to FGS, some portion of the window must be located within the sensing range. When the teach mode is set to BGS, the offset value must be within the defined sensing range. If an offset value falls outside of the sensing range, a message displays. See the applicable TEACH procedure for more information.

## 3.2.12 Display View

Use this menu to select the display view. The default is right-reading.

- Right-reading
- hearted
- —Right-reading and the display enters sleep mode after 60 seconds
- 🛨 💆 —Inverted and the display enters sleep mode after 60 seconds

When the sensor is in sleep mode, the display wakes with the first button press.

## 3.2.13 Exit Setup Mode

Navigate to and press SELECT to exit Setup mode and return to Run mode.

## 3.2.14 Reset to Factory Defaults

Use this menu to restore the sensor to the factory default settings. See Factory Default Settings on page 16.

Select  $\frac{72}{25}$  to return to the sensor menu without restoring the defaults. Select  $\frac{75}{25}$  to apply the factory defaults and return to Run mode.

#### **Factory Default Settings**

Setting	Factory Default
Delay Timers (	□FF —No delay
Display View ( 5 , 5 )	문경기 —Right-reading, no sleep mode
Gain and Sensitivity ( The unit )	H ICH —High excess gain mode
Output (호파트 등 호파트로)	L 0 —Light Operate
Response Speed ( 5 5 0 )	₩ —10 ms for 100/110 and 300/310 models
	—25 ms for 600/610 models
Shift the Zero Reference Location after a TEACH ( 5 h )	-0 = the front of the sensor
TEACH Mode ( )	Two-point TEACH —Two-point TEACH
Zero Reference Location (	—Measurement increases further from sensor

## 3.3 Manual Adjustments

Manually adjust the sensor switch point using the  $^{\scriptsize\textcircled{+}}$  and  $^{\scriptsize\textcircled{-}}$  buttons.

- 1. From Run mode, press either or one time. The selected channel displays briefly, then the current switch point value flashes slowly.
- 2. Press to move the switch point up or to move the switch point down. After 1 second of inactivity, the new switch point value flashes rapidly, the new setting is accepted, and the sensor returns to Run mode.



Note: When FGS mode is selected (FGS indicator is on), manual adjustment moves both sides of the symmetrical threshold window simultaneously, expanding and collapsing the window size. Manual adjustment does not move the center point of the window.



Note: When dual mode is selected (DYN, FGS, and BGS indicators are on), after the TEACH process is completed, use the manual adjustment to adjust the sensitivity of the thresholds around the taught reference point. The taught reference point is a combination of the measured distance and returned signal intensity from the reference target. Manual adjustment does

not move the taught reference point, but pressing increases the sensitivity, and pressing decreases the sensitivity. When re-positioning the sensor or changing the reference target, re-teach the sensor.

### 3.4 Remote Input

Remote input is available from the Channel 2 menu. Set Out2 to Set.

Use the remote input to program the sensor remotely. The remote input provides limited programming options and is Active high. For Active high, connect the white input wire to ground (0 V dc), with a remote switch connected between the wire and ground. Pulse the remote input according to the diagram and the instructions provided in this manual.

The length of the individual programming pulses is equal to the value T: 0.04 seconds T 0.8 seconds.

Exit remote programming modes by setting the remote input high for longer than 2 seconds.

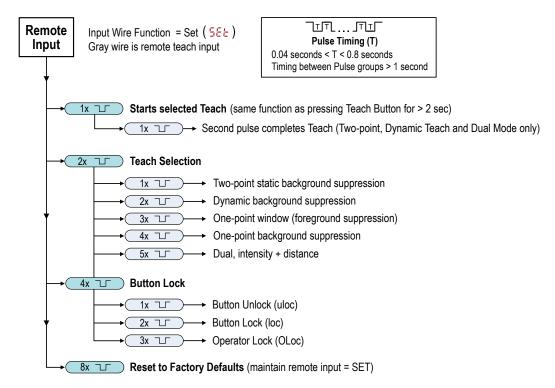
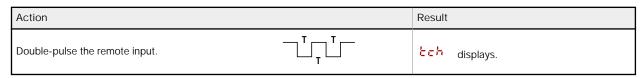


Figure 16. Remote Input Map

#### 3.4.1 Select the TEACH Mode Using the Remote Input

1. Access the TEACH selection.



2. Select the desired TEACH mode.

Action		Result
Pulses	TEACH Mode	
1	Two-point static background suppression	
2	Dynamic background suppression	
3 7 7 7 7	One-point window (foreground suppression)	The selected TEACH method displays for a few seconds and the sensor returns to Run mode.
4	One-point background suppression	
5 7 7 7 7 7	Dual (intensity + distance)	

### 3.4.2 Reset to Factory Defaults Using the Remote Input

Eight-pulse the remote input to apply the factory defaults and return to Run mode.





Note: The input wire function remains at remote teach input (  $55 \pm 1$  ).

## 3.5 Locking and Unlocking the Sensor Buttons

Use the lock and unlock feature to prevent unauthorized or accidental programming changes. Three settings are available:

- Land The sensor is unlocked and all settings can be modified (default).
- Loc
   The sensor is locked and no changes can be made.
- The switch point value can be changed by teaching or manual adjustment, but no sensor settings can be changed through the menu.



Note: When the sensor is in either or when the active channel can be changed using (+)(CH1/CH2).

When in Local mode, Local displays when the (SELECT)(TEACH) button is pressed. The switch point displays when (+)(CH1/CH2) or (-)(MODE) are pressed, but Local displays if the buttons are pressed and held.

When in the mode, the mode, displays when (-)(MODE) is pressed and held. To access the manual adjust options, briefly press and release (+)(CH1/CH2) or (-)(MODE). To enter TEACH mode, press the (SELECT)(TEACH) button and hold for longer than 2 seconds.

#### **Button Instructions**

To enter the mode, hold and press four times. To enter the mode, hold and press four times. Holding and pressing four times unlocks the sensor from either lock mode and the sensor displays for times unlocks the sensor from either lock mode and the sensor displays for times.

#### Remote Input Instructions

1. Access the remote input.

Action	Result
Four-pulse the remote input.	The sensor is ready to have the button state defined and displays.

#### 2. Lock or unlock the sensor buttons.

Action	Result
Single-pulse the remote input to unlock the sensor.	 Run mode.
Double-pulse the remote input to lock the sensor.	 displays and the sensor returns to Run mode.
Triple-pulse the remote input to apply the operator lock to the sensor	CL DC displays and the sensor returns to Run mode

### 3.6 TEACH Procedures

Use the following procedures to teach the sensor.

To cancel a TEACH procedure, press TEACH for longer than 2 seconds, or hold the remote input high for longer than 2 seconds.

The momentarily displays when a TEACH procedure is canceled.

After any teach operation starts, the display temporarily flashes CH1 or CH2 to confirm which channel is currently selected.

## 3.6.1 Two-Point Static Background Suppression

Two-point TEACH sets a single switch point. The sensor sets the switch point between two taught target distances, relative to the shifted origin location.

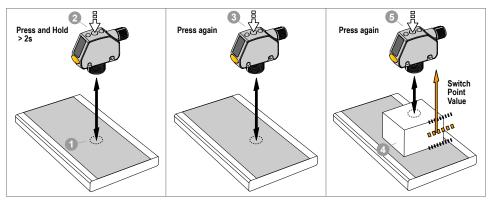


Figure 17. Two-Point Static Background Suppression (Light Operate shown)



Note: The sensor must be set to  $\frac{1}{2} \frac{1}{2} \frac{1}{12} = \frac{1}{2} \frac{1}{2} \frac{1}{12} \frac{1}{2}$  to use the following instructions.



### 1. Present the target.

Method	Action	Result
Push Button	Present the first target. The sensor-to-target distance must be within the	The target's measurement value
Remote Input	sensor's range.	displays.

#### 2. Start the TEACH mode.

Method	Action	Result
Push Button	Press and hold TEACH for longer than 2 seconds.	on the display. The DYN, FGS, and BGS indicators flash.
Remote Input	No action required.	N/A

### 3. Teach the sensor.

Method	Action	Result
Push Button	Press TEACH to teach the target.	The sensor is taught the first target.
Remote Input	Single-pulse the remote input.	556 , 200 , and the current distance measurement flash alternately on the display. The DYN, FGS, and BGS indicators flash.

### 4. Present the target.

Method	Action	Result
Push Button		565 , 2nd , and the distance
Remote Input	Present the second target. The sensor-to-target distance must be within the sensor's range.	measurement flash alternately on the display. The DYN, FGS, and BGS indicators flash.

#### 5. Teach the sensor.

Method	Action	Result
Push Button	Press TEACH to teach the target.	
Remote Input	Single-pulse the remote input.	The new switch point flashes rapidly and the sensor returns to Run mode.

Table 3: Expected TEACH Behavior for Two-Point Static Background Suppression See Figure 23 on page 34 for the minimum object separation.

Condition	TEACH Result	Display
Two valid distances that are greater than or equal to the horizontal minimum object separation	Sets a switch point between the two taught distances.	The switch point distance flashes on the display.
Two valid distances that are less than the horizontal minimum object separation	Sets a switch point in front of the furthest taught distance by the horizontal minimum object separation.	and the switch point distance flash alternately on the display.
One valid distance with one invalid TEACH point	Sets a switch point between the one taught distance and the maximum range.	and the switch point distance flash alternately on the display.

Condition	TEACH Result		Display
Two invalid TEACH points	Sets a switch point at the following location:		and the switch point distance
	Model	Switch Point	flash alternately on the display.
	100 mm threaded barrel models	99	
	300 mm threaded barrel models	290	
	600 mm threaded barrel models	590	
	110 mm flush mount models	109	
	310 mm flush mount models	300	
	610 mm flush mount models	600	

## 3.6.2 Dynamic Background Suppression

Dynamic TEACH sets a single switch point during machine run conditions. Dynamic TEACH is recommended for applications where a machine or process may not be stopped for teaching. The sensor takes multiple samples and the switch point is set between the minimum and the maximum sampled distances.

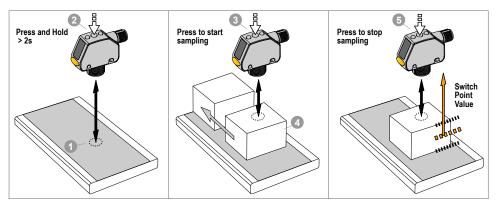


Figure 18. Dynamic Background Suppression



Note: The sensor must be set to  $= \frac{1}{2} \frac{1}{2} \frac{1}{12} \frac{1}{1$ 



#### 1. Present the target.

Method	Action	Result
Push Button	Present the first target. The sensor-to-target distance must be within the	The target's measurement value
Remote Input	sensor's range.	displays.

#### 2. Start the TEACH mode.

Method	Action	Result
Push Button	Press and hold TEACH for longer than 2 seconds.	and fishes. flash alternately on the display. The DYN indicator flashes.
Remote Input	No action required.	N/A

#### 3. Teach the sensor.

Method	Action	Result
Push Button	Press TEACH to teach the target.	The sensor begins sampling target
Remote Input	Single-pulse the remote input.	distance information and distance and figure

#### 4. Present the targets.

Method	Action	Result
Push Button		The sensor continues to sample target
Remote Input		distance information and distance and stance information and distance and stance and sta

#### 5. Teach the sensor.

Method	Action	Result
Push Button	Press TEACH to stop teaching the sensor.	T
Remote Input	Single-pulse the remote input.	The new switch point flashes rapidly and the sensor returns to Run mode.

Table 4: Expected TEACH Behavior for Dynamic Background Suppression See Figure 23 on page 34 for the minimum object separation.

Condition	TEACH Result		Display
Two valid distances that are greater than or equal to the horizontal minimum object separation	Sets a switch point between the two taught distances.		The switch point distance flashes on the display.
Two valid distances that are less than the horizontal minimum object separation	Sets a switch point in front of the furthest taught distance by the horizontal minimum object separation.		and the switch point distance flash alternately on the display.
One valid distance with one invalid TEACH point	Sets a switch point between the one taught distance and the maximum range.		and the switch point distance flash alternately on the display.
Two invalid TEACH points	Sets a switch point at the following location:		and the switch point distance
	Model	Switch Point	flash alternately on the display.
	100 mm threaded barrel models	75	
	300 mm threaded barrel models	200	
	600 mm threaded barrel models	400	
	110 mm flush mount models	85	
	310 mm flush mount models	210	
	610 mm flush mount models	410	

## 3.6.3 One-Point Window (Foreground Suppression)

One-point window sets a window (two switch points) centered around the taught target distance. Loss of signal is treated as a detection in One-Point Window mode. The size of the taught window is the vertical minimum object separation. See *Figure 23* on page 34.

Manually adjust the window size from Run mode using  $\begin{tabular}{c} \bullet \end{tabular}$  and  $\begin{tabular}{c} \bullet \end{tabular}$  .

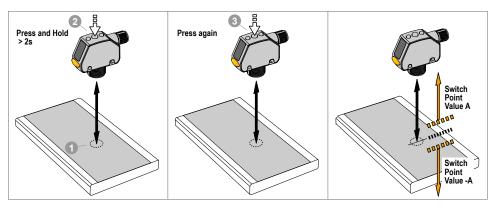


Figure 19. One-Point Window (Foreground Suppression)

In order to reliably detect changes from the taught background, if multiple laser **reflections** are returning to the sensor, the output status is treated as though the target is outside of the taught window. The display alternates between distance. Realign the laser to avoid light **reflecting** off of multiple targets if this extra level of **verification** is not desired.



Note: The sensor must be set to  $\frac{1}{2}$  to use the following instructions. The FGS indicator is amber to indicate One-Point Window (Foreground Suppression) mode.



Note: To program the sensor using remote input, remote input must be enabled ( $\frac{\mathbf{p}_{\mathbf{q}} \mathbf{p}_{\mathbf{q}}^{\mathbf{p}_{\mathbf{q}}} \mathbf{p}_{\mathbf{q}}^{\mathbf{p}_{\mathbf{q}}} = \frac{\mathbf{p}_{\mathbf{q}}^{\mathbf{p}_{\mathbf{q}}} \mathbf{p}_{\mathbf{q}}^{\mathbf{p}_{\mathbf{q}}}}{\mathbf{p}_{\mathbf{q}}^{\mathbf{p}_{\mathbf{q}}} \mathbf{p}_{\mathbf{q}}^{\mathbf{p}_{\mathbf{q}}} \mathbf{p}_{\mathbf{q}}^{\mathbf{p}_{\mathbf{q}}} \mathbf{p}_{\mathbf{q}}^{\mathbf{p}_{\mathbf{q}}}$ ).

#### 1. Present the target.

Method	Action	Result
Push Button	Present the target. The sensor-to-target distance must be within the	The target's measurement value
Remote Input	sensor's range.	displays.

#### 2. Start the TEACH mode.

Method	Action	Result
Push Button	Press and hold TEACH for longer than 2 seconds.	Light Operate  55 and 50 flash alternately on the display. The FGS indicator flashes.  Dark Operate  55 and 55 flash alternately on the display. The FGS indicator flashes.
Remote Input	No action required.	N/A

#### 3. Teach the sensor.

Method	Action	Result
Push Button	Press TEACH to teach the target.	
Remote Input	Single-pulse the remote input.	The ± window size flashes rapidly and the sensor returns to Run mode.

Table 5: Expected TEACH Behavior for One-Point Window (Foreground Suppression)
See Figure 23 on page 34 for the minimum object separation.

Condition	TEACH Result		Display
One valid TEACH point with both switch points in range (with offset, if applicable)	Sets a window (two switch points) centered around the taught distance. The ± window size is the vertical minimum object separation. The two switch points always stay within the specified sensing range.		The ± window size flashes on the display.
One invalid TEACH Point	Sets a window (two switch points) centered around the following location:		and the window center point distance flash alternately on the
	Model	Window Center Point	display.
	100 mm threaded barrel models	80	
	300 mm threaded barrel models	250	
	600 mm threaded barrel models	500	
	110 mm flush mount models	90	
	310 mm flush mount models	260	
	610 mm flush mount models	510	
	The window size is:		
	Model	Window Size	
	100 mm threaded barrel and 110 mm flush mount models	±12.5 mm	
	300 mm threaded barrel and 310 mm flush mount models	± 25 mm	
	600 mm threaded barrel and 610 mm flush mount models	± 25 mm	
One valid TEACH point with one switch point within range and one switch point out of range (with offset, if applicable)	Sets a window (two switch points) that is centered at the TEACH point (after offset, if applicable) with one switch point at the maximum range.		and the ± window size flash alternately on the display.

Condition	TEACH Result		Display
One valid TEACH point that, after the offset, results in a both switch points outside of the range	Sets a window (two switch points) centered around the following location:		and the window center point distance flash alternately on the
January S. J.	Model	Window Center Point	display.
	100 mm threaded barrel models	80	
	300 mm threaded barrel models	250	
	600 mm threaded barrel models	500	
	110 mm flush mount models	90	
	310 mm flush mount models	260	
	610 mm flush mount models	510	
	The window size is:		
	Model	Window Size	
	100 mm threaded barrel and 110 mm flush mount models	±12.5 mm	
	300 mm threaded barrel and 310 mm flush mount models	± 25 mm	
	600 mm threaded barrel and 610 mm flush mount models	± 25 mm	

## 3.6.4 One-Point Background Suppression

One-point background suppression sets a single switch point in front of the taught target distance. Objects beyond the taught switch point are ignored. The switch point is set in front of the taught target distance by the vertical minimum object separation. See *Figure 23* on page 34.

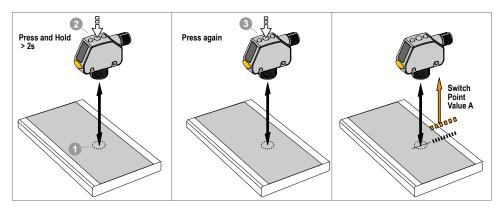


Figure 20. One-Point Background Suppression



Note: The sensor must be set to  $= \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}$  to use the following instructions. The BGS indicator is amber to indicate Background Suppression mode.



1. Present the target.

Method	Action	Result
Push Button	Present the target. The sensor-to-target distance must be within the	The target's measurement value
Remote Input	sensor's range.	displays.

#### 2. Start the TEACH mode.

Method	Action	Result
Push Button	Press and hold TEACH for longer than 2 seconds.	Light Operate  55 and 55 flash alternately on the display. The BGS indicator flashes.  Dark Operate  55 and 55 flash alternately on the display. The BGS indicator flashes.
Remote Input	No action required.	N/A

#### 3. Teach the sensor.

Method	Action	Result
Push Button	Press TEACH to teach the target.	
Remote Input	Single-pulse the remote input.	The new switch point flashes rapidly and the sensor returns to Run mode.

Table 6: Expected TEACH Behavior for One-Point Background Suppression See Figure 23 on page 34 for the minimum object separation.

Condition	TEACH Result		Display
One valid TEACH point  If an Offset is applied, the TEACH point is still valid	Sets a switch point in front of the taught distance by the vertical minimum object separation.		The switch point distance flashes on the display.
One invalid TEACH point	Sets a switch point at the follow	ving location:	and the switch point distance
	Model	Switch Point	flash alternately on the display.
	100 mm threaded barrel models	75	
	300 mm threaded barrel models	200	
	600 mm threaded barrel models	400	
	110 mm flush mount models	85	
	310 mm flush mount models	210	
	610 mm flush mount models	410	

Condition	TEACH Result		Display
One valid TEACH point that, after offset, becomes invalid	Sets a switch point at the following location:		and the switch point distance
	Model	Switch Point	flash alternately on the display.
	100 mm threaded barrel models	75	
	300 mm threaded barrel models	200	
	600 mm threaded barrel models	400	
	110 mm flush mount models	85	
	310 mm flush mount models	210	
	610 mm flush mount models	410	
		•	

## 3.6.5 Dual (Intensity + Distance)

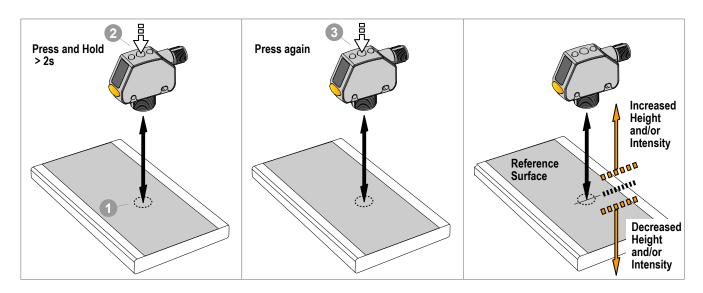
Dual (intensity + distance) TEACH records the distance and amount of light received from the reference surface. The output switches when an object passing between the sensor and the reference surface changes the perceived distance or amount of returned light. For more information on dual TEACH mode, see *Dual (Intensity + Distance) Mode* on page 36.



Note: To use the following instructions, set the sensor to  $\frac{1}{2}$   $\frac{1}{2}$   $\frac{1}{2}$  . The DYN, FGS, and BGS indicators are amber



Note: To program the sensor using remote input, remote input must be enabled ( $\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2} = \frac{1}{2} \frac{1}{2} \frac{1}{2}$ ).



#### 1. Present the target.

Method	Action	Result
Push Button	Present the reference target.	The target's match percentage displays
Remote Input	Present the reference target.	The target's match percentage displays

#### 2. Start the TEACH mode.

Method	Action	Result
Push Button	Press and hold the TEACH button for more than 2 seconds.	Light Operate: 565 and 576 flash on the display. The DYN, FGS, and BGS indicators flash.  Dark Operate: 565 and 576 flash on the display. The DYN, FGS, and BGS indicators flash.
Remote Input	No action required.	N/A

#### 3. Teach the sensor.

Method	Action	Result
Push Button	Press the TEACH button.	T
Remote Input	Single-pulse the remote input.	The switching threshold flashes rapidly and the sensor returns to Run mode.

Table 7: Expected TEACH Behavior for Dual (Intensity + Distance) Mode

Condition	TEACH Result	Display
One valid reference surface is taught within sensing range	Sets a dual (intensity + distance) window centered around the taught reference surface. The ± window size is the previously used switching threshold, or 75% by default.	The switching threshold flashes on the display.
One reference surface is taught outside the sensing range	Sets a dual (intensity + distance) window centered around the taught reference surface that is outside the sensing range. The sensing conditions may not be as reliable.	្នាក់ flashes on the display.
One invalid TEACH Point	No reference surface is taught, the output will change when any object is detected.	Full flashes on the display.

## 3.7 Pulse Frequency Modulation (PFM) Output

The Q4X can generate pulses whose frequency are proportional to the sensor's measured distance, thereby providing a method for representing an analog signal with only a discrete counter. The sensing range of the sensor is scaled from 100 to 600 Hz (100 Hz equals the near range limit of the sensor, 600 Hz equals the far sensing range limit). An output of 50 Hz represents a Loss of Signal ( LD5) condition where there is no target or the target is out of the sensor's range.

## 3.8 Sync Master/Slave

Two Q4X sensors may be used together in a single sensing application. To eliminate crosstalk between the two sensors, **configure** one sensor to be the master and one to be the slave. In this mode, the sensors alternate taking measurements and the response speed doubles.



Important: The master sensor and the slave sensor must be programmed for the same Response Speed and Gain and Sensitivity settings. The master sensor and slave sensor must share a common power source.

- 3. Connect the gray (input) wires of the two sensors together.

## 4 IO-Link Interface

IO-Link is a point-to-point communication link between a master device and sensor. It can be used to automatically parameterize sensors and transmit process data. For the latest IO-Link protocol and **specifications**, please visit the web site at <a href="http://www.io-link.com">http://www.io-link.com</a>.

The IO-Link IODD package (P/N 196929) is contained on the Banner Website at http://www.bannerengineering.com.

## **5 Specifications**

Sensing Beam

Visible red Class 1 laser, 655 nm

Supply Voltage (Vcc)

10 to 30 V dc (Class 2 supply) (10% max ripple within limits)

Power and Current Consumption, exclusive of load

< 700 mW

Sensing Range—Threaded Barrel Models

600 mm models: 25 mm to 600 mm (0.98 in to 23.62 in) 300 mm models: 25 mm to 300 mm (0.98 in to 11.81 in)

100 mm models: 25 mm to 100 mm (0.98 in 3.94 in)

Sensing Range—Flush Mount Models

610 mm models: 35 mm to 610 mm (1.38 in to 24.02 in) 310 mm models: 35 mm to 310 mm (1.38 in to 12.20 in) 110 mm models: 35 mm to 110 mm (1.38 in to 4.33 in)

Output Configuration

First output = IO-Link, Push/pull

Secondary output = PNP only output or input, or pulse frequency modulated output

Output Rating

100 mA max capability each output

100 mA max total load current for sensor

Saturation: < 2 V

Off-state leakage current: < 50 µA PNP at 30 V (N.A. push/pull)

Discrete Output Distance Repeatability

Table 8: 600/610 mm Models

Distance (mm)		Repeatability
Threaded Barrel Models Flush Mount Models		
25 to 100 mm	35 to 110 mm	± 0.5 mm
100 to 600 mm	110 to 610 mm	± 0.5%

#### Table 9: 300/310 mm Models

Distance (mm)		Repeatability
Threaded Barrel Models Flush Mount Models		
25 to 50 mm	35 to 60 mm	± 0.5 mm
50 to 300 mm	60 to 310 mm	± 1% of range

#### Table 10: 100/110 mm Models

Distance (mm)		Repeatability
Threaded Barrel Models Flush Mount Models		
25 to 100 mm	35 to 110 mm	+/-0.2 mm

Remote Input

Allowable Input Voltage Range: 0 to Vcc

Active High (internal weak pulldown): High state > (VCC - 2 V) @ 1.5 mA max.

Supply/Output Protection Circuitry

Protected against reverse polarity and transient overvoltages

Response Speed

User selectable, 100, 110, 300, and 310 mm models:

—1.5 milliseconds

• ∃—3 milliseconds

• —10 milliseconds

—25 milliseconds

• 50 —50 milliseconds

User selectable, 600 and 610 mm models:

€ —2 milliseconds

5 —5 milliseconds

- — 3 IIIIII seconds

—15 milliseconds

—25 milliseconds

50 —50 milliseconds

Delay at Power Up

100, 110, 300, 310 mm models: < 750 ms

600, 610 mm models: < 1.5 s

Maximum Torque

Side mounting: 1 N·m (9 in·lbs)

Nose mounting: 20 N·m (177 in·lbs)

Ambient Light Immunity

> 5,000 lux at 300 mm

> 2,000 lux at 600 mm

Connector

Integral 4-pin M12/Euro-style male quick disconnect (QD)

Construction

Housing: 316 L stainless steel

Lens cover: PMMA acrylic

Lightpipe and display window: polysulfone

Temperature Effect

0.05 mm/°C at < 125 mm (threaded barrel models)/< 135 mm (flush

mount models)

0.35 mm/°C at 300 mm (threaded barrel models)/310 mm (flush mount

models)

1.0 mm/ $^{\circ}\text{C}$  at 600 mm (threaded barrel models)/ 610 mm (flush mount

models)

**Chemical Compatibility** 

Compatible with commonly used acidic or caustic cleaning and

disinfecting chemicals used in equipment cleaning and sanitation. ECOLAB® certified.

Compatible with typical cutting fluids and lubricating fluids used in machining centers

IO-Link Interface

Supports Smart Sensor Profile: Yes

Baud Rate: 38400 bps

Process Data Widths: 16 bits

IODD files: Provides all programming options of the display, plus

additional functionality.

Application Note

For optimum performance, allow 10 minutes for the sensor to warm up

#### Beam Spot Size—100/110 mm Models

Table 11: Beam Spot Size—100/110 mm Models

Distance (mm)		Size (Horizontal × Vertical)
Threaded Barrel Models	Flush Mount Models	
25	35	2.4 mm × 1.0 mm
50	60	2.2 mm × 0.9 mm
100	110	1.8 mm × 0.7 mm

#### Beam Spot Size—300/310 mm and 600/610 mm Models

Table 12: Beam Spot Size—300/310 mm and 600/610 mm Models

Distance (mm)		Size (Horizontal × Vertical)
Threaded Barrel Models	Flush Mount Models	vertical)
25	35	2.6 mm × 1.0 mm
150	160	2.3 mm × 0.9 mm
300	310	2.0 mm × 0.8 mm
600	610	1.9 mm × 1.0 mm

#### Excess Gain using a 90% White Card—100/110/300/310 mm Models

Table 13: H ICH Excess Gain ( 555 Excess Gain 1)

Response Speed (ms)	· at 25 mm (100/300 mm models) · at 35 mm (110/310 mm models)	· at 100 mm (100/300 mm models) · at 110 mm (110/310 mm models)	· at 300 mm (100/300 mm models) · at 310 mm (110/310 mm models)
1.5	200	100	20
3	200	100	20
10	1000 (500)	500 (250)	100 (50)
25	2500 (1000)	1250 (500)	250 (100)
50	5000 (2500)	2500 (1250)	500 (250)

#### Excess Gain using a 90% White Card—600/610 mm Models

Table 14: H IGH Excess Gain ( 55 d Excess Gain<sup>2</sup>)

Response Speed (ms)	· at 25 mm (600 mm models) · at 35 mm (610 mm models)	<ul> <li>at 100 mm (600 mm models)</li> <li>at 110 mm (610 mm models)</li> </ul>	<ul> <li>at 300 mm (600 mm models)</li> <li>at 310 mm (610 mm models)</li> </ul>	· at 600 mm (600 mm models) · at 610 mm (610 mm models)
2	280	110	25	6
5	280	110	25	6
15	1000 (360)	400 (150)	80 (30)	20 (7)
25	2000 (1000)	800 (400)	160 (80)	40 (20)
50	4000 (2000)	1600 (800)	320 (160)	80 (40)

Environmental Rating

IEC IP67 per IEC60529

IEC IP68 per IEC60529

IEC IP69K per DIN40050-9

### Vibration

MIL-STD-202G, Method 201A (10 Hz to 60 Hz, 0.06 inch (1.52 mm) double amplitude, 2 hours each along X, Y and Z axes), with sensor operating

#### Shock

MIL-STD-202G, Method 213B, Condition I (100G 6x along X, Y and Z axes, 18 total shocks), with sensor operating

Operating Conditions

 $-10~^{\circ}\text{C}$  to +50  $^{\circ}\text{C}$  (+14  $^{\circ}\text{F}$  to +122  $^{\circ}\text{F}$ )

35% to 95% relative humidity

Storage Temperature

-25 °C to +75 °C (-13 °F to +167 °F)

555 excess gain available in 10 ms, 25 ms, and 50 ms response speeds only

excess gain provides increased noise immunity

. Secretary excess gain available in 15 ms response speed only

• excess gain provides increased noise immunity

<sup>1</sup> 

#### Required Overcurrent Protection



WARNING: Electrical connections must be made by qualified personnel in accordance with local and national electrical codes and regulations.

Overcurrent protection is required to be provided by end product application per the supplied table.

Overcurrent protection may be provided with external fusing or via Current Limiting, Class 2 Power Supply.

Supply wiring leads < 24 AWG shall not be spliced.

For additional product support, go to www.bannerengineering.com.

Supply Wiring (AWG)	Required Overcurrent Protection (Amps)
20	5.0
22	3.0
24	2.0
26	1.0
28	0.8
30	0.5

#### Certifications





Class 2 power

UL Environmental Rating: Type 1



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## 5.1 Dimensions

All measurements are listed in millimeters [inches], unless noted otherwise.

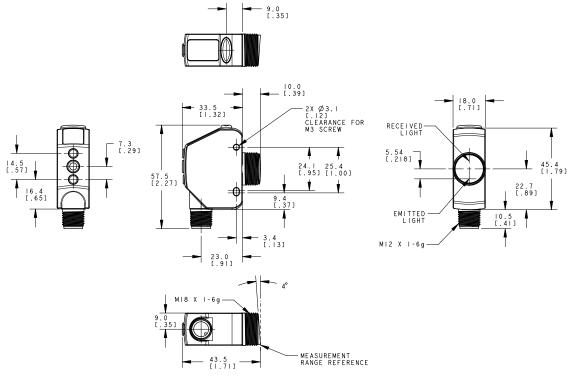


Figure 21. Threaded Barrel Models

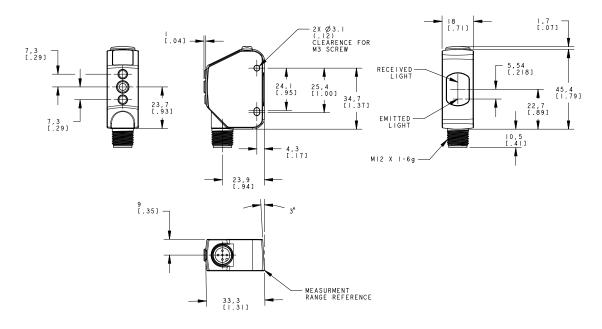
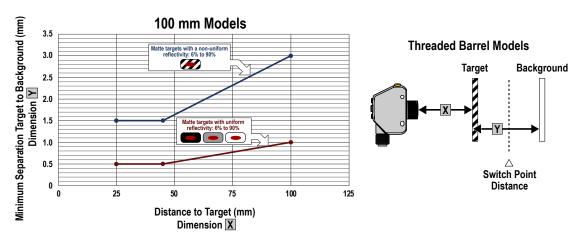


Figure 22. Flush Mount Models

### 5.2 Performance Curves—Threaded Barrel Models

### Minimum Separation Distance Between Target and Background for: Uniform and Non-Uniform Targets



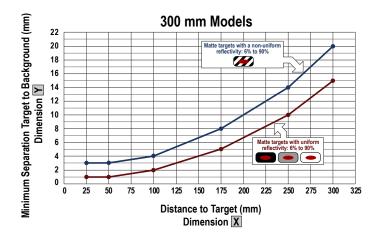
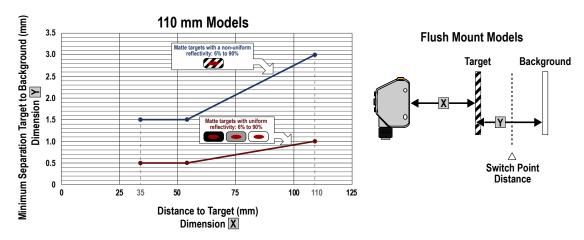


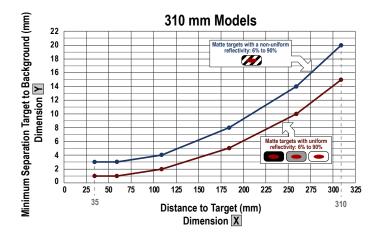


Figure 23. Minimum Object Separation Distance (90% to 6% reflectance)

### 5.3 Performance Curves—Flush Mount Models

### Minimum Separation Distance Between Target and Background for: Uniform and Non-Uniform Targets





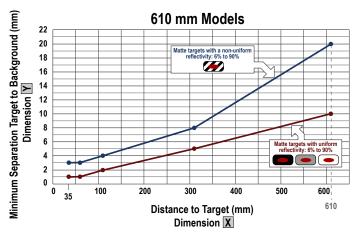


Figure 24. Minimum Object Separation Distance (90% to 6% reflectance)

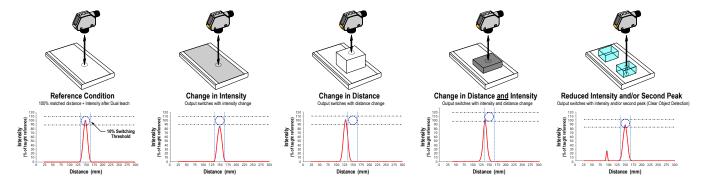
## 6 Additional Information

### 6.1 Dual (Intensity + Distance) Mode

In background suppression (DYN, 1-pt, 2-pt) and foreground suppression (FGS) TEACH modes, the Q4X sensor compares changes in the measured distance between the sensor and target to control the output state. Dual TEACH mode, dual intensity + distance window, expands the applications the Q4X can solve by combining distance-based detection with light intensity thresholds. In dual TEACH mode, the user teaches the Q4X a fixed reference surface, and the sensor compares intensity and distance readings against the reference surface it was taught. After teaching the reference target, the displayed value is calibrated to 100P, or a 100% match. When an object enters the sensor's field of view, the degree of consistency with the reference surface becomes lower and causes a change in sensor output.

In dual mode, you can detect when the target is present at the right distance and when it returns the right amount of light. This is useful in error-proofing applications where you need to know not only that the part is present (distance), but also that it is the correct part (intensity).

In dual mode, the Q4X requires a reference surface (far left). Once taught, the distance and intensity of the reference surface are recorded and used as a baseline. A user adjustable switching threshold is set, and changes in distance and/or intensity outside the switching threshold creates a sensor output change. The example above uses a 90% (90P) match condition with a 10% change in intensity and/or distance from the reference surface required to change the output state. The default-switching threshold is a 75% match to the reference condition (75P); this sets the threshold 25% from the distance and intensity of the reference surface. A transparent object can be detected either by a change in intensity, distance, or by a double peak reflection (far right). When a double peak reflection is detected, the display alternates between



The Q4X sensor can be taught non-ideal reference surfaces, such as surfaces outside of the sensor's range, very dark surfaces, or even empty space. These situations may enable applications requiring a long range detection but are subject to typical diffuse mode detection challenges.

### 6.2 Dual Mode Reference Surface Considerations

Optimize reliable detection by applying these principals when selecting your reference surface, positioning your sensor relative to the reference surface, and presenting your target. The robust detection capabilities of the Q4X allows successful detection even under non-ideal conditions in many cases. Typical reference surfaces are metal machine frames, conveyor side rails, or mounted plastic targets. Contact Banner Engineering if you require assistance setting up a stable reference surface in your application.

- 1. Select a reference surface with these characteristics where possible:
  - · Matte or diffuse surface finish
  - · Fixed surface with no vibration
  - Dry surface with no build-up of oil, water, or dust
- 2. Position the reference surface between 50 mm and the maximum sensing range for threaded barrel models or between 60 mm and the maximum sensing range for flush mount models.
- 3. Position the target to be detected as close to the sensor as possible, and as far away from the reference surface as possible.
- 4. Angle the sensing beam relative to the target and relative to the reference surface 10 degrees or more.

## 6.3 Dual Mode Considerations for Clear and Transparent Object Detection

The Q4X is able to detect the very small changes caused by transparent and clear objects. A transparent object can be detected either by a change in intensity, distance, or by a double-peak reflection.

The Q4X sensor can be taught non-ideal reference surfaces, such as surfaces outside of the sensor range or very dark surfaces. Teaching non-ideal reference surfaces may enable applications other than transparent or clear object detection, but best results for transparent or clear object detection require a stable reference surface.

The display shows the match percentage to the taught reference point. The user adjustable switch point defines the sensitivity and the output switches when the match percentage to the reference point crosses the switch point. Your specific application may require fine tuning of the switch point, but these values are the recommended starting values:

Switch point (%)	Typical Applications
75 (default)	Default, recommended for PET bottles and Trays
88	Recommended for thin films
50	Recommended for tinted brown, tinted green, or water-filled containers

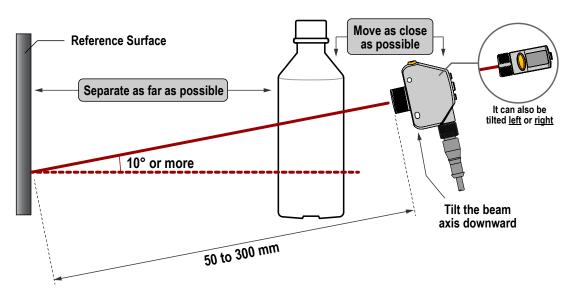


Figure 25. Example mounting considerations

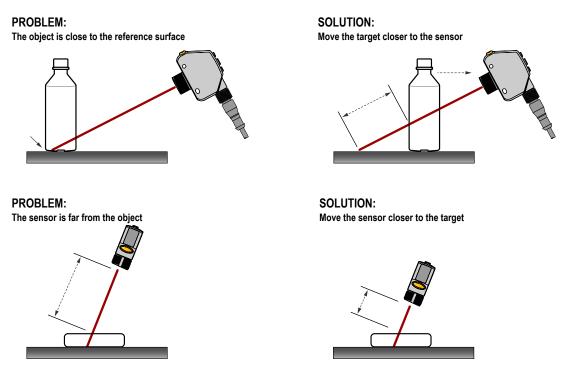


Figure 26. Common problems and solutions for detecting clear objects

## 6.4 Abbreviations

The following table describes the abbreviations used on the sensor display and in this manual.

Abbreviation	Description
	No valid signal in range
999P	The sensor has not been taught
15ho	One-shot
15E	First
8-6-	Multiple light reflections
čná	Second
2-Pb	Two-point TEACH (static background suppression)
Auto	Automatic
505	One-point background suppression
bbn	Button
ChCL	Cancel
CoAP	Complementary output
d (SP	Display read
47 8A	Delay
97.2.1 ' 97.25	Output timing delay (Channel 1, Channel 2)
do	Dark operate
db 1 , db2	Delay timer (Channel 1, Channel 2)
duRL	Dual mode
dan	Dynamic background suppression
End	End—exit the sensor menu
FA-	Far zero reference location—the maximum range is 0 and the measurement increase as the target moves closer to the sensor
FGS	One-point window (foreground suppression)
Full	Full range
58 m	Excess gain
H ICH	High excess gain mode
H5	High speed tracking
Lo	Light operate
Lon	Laser on

Abbreviation	Description
Loc	Lock/locked
Loff	Laser off
ARSE	Master
nEAr	Near zero reference location—the front of the sensor is 0 and the measurement increase as the target moves further away from the sensor
abult	Object
ofd:, ofd2	Off delay timer (Channel 1, Channel 2)
off	Off
oF51, oF52	Offset (Channel 1, Channel 2)
oFSE	An applied offset resulted in an invalid switch point
on.	On
and I, andč	On delay timer (Channel 1, Channel 2)
out 1, out?	Output (Channel 1, Channel 2)
PULS	Pulse frequency modulation
F586	Reset to factory defaults
SAUE	Save
588	Set or Input wire = remote teach function
ShFE	Shift the Zero Reference Location after a TEACH
SLUE	Slave
SPa	Response speed
56 <i>d</i>	Standard excess gain mode
Strt	Start
StoP	Stop
beh I, behê	TEACH process selection (Channel 1, Channel 2)
toti	Totalizer
tot 1, tot2	Total counts
ulac	Unlock/unlocked
non	Saturated signal (too much light)
ünd I, ündê	Window size (Channel 1, Channel 2)
985	Yes
∂6ro	Zero—select the zero reference location

## 7 Troubleshooting

Table 15: Error Codes

Error Code	Description	Resolution
	No valid signal in range	Reposition the sensor or the target
מטטט	The signal is saturated (too much light)	Reposition the sensor or the target to increase the detection distance, or increase the angle of incidence between the sensor and the target
ErrE	EEPROM fault	Contact Banner Engineering to resolve
Enri	Laser fault	Contact Banner Engineering to resolve
En-C	Output short-circuited	Check the wiring for an electrical short circuit and to ensure that the wiring is correct
ErrS	System fault	Contact Banner Engineering to resolve

## 8 Accessories

## 8.1 Cordsets

4-Pin Threaded M12/Euro-Style Cordsets				
Model	Length	Style	Dimensions	Pinout (Female)
MQDC-406	1.83 m (6 ft)	Straight		
MQDC-415	4.57 m (15 ft)			
MQDC-430	9.14 m (30 ft)			
MQDC-450	15.2 m (50 ft)		M12 x 1 -   ø 14.5 -	1 2
MQDC-406RA	1.83 m (6 ft)	Right-Angle	32 Typ.	4
MQDC-415RA	4.57 m (15 ft)		[1.26"]	
MQDC-430RA	9.14 m (30 ft)		30 Typ.	1 = Brown 2 = White
MQDC-450RA	15.2 m (50 ft)		M12 x 1 0 14.5 [0.57"]	3 = Blue 4 = Black

4-Pin Threaded M12/Euro-Style Cordsets—Washdown, Stainless Steel				
Model	Length	Style	Dimensions	Pinout (Female)
MQDC-WDSS-0406	1.83 m (6 ft)			
MQDC-WDSS-0415	4.57 m (15 ft)	Straight		1-0-2
MQDC-WDSS-0430	0.14 == (30.6)		Ø15.5 mm	4 3
	9.14 m (30 ft)		43.5 mm —	1 = Brown 2 = White
				3 = Blue 4 = Black

4-Pin Threaded M12/Euro-Style Cordsets—Double Ended				
Model	Length	Style	Dimensions	Pinout
MQDEC-401SS	0.31 m (1 ft)	Male Straight/ Female Straight		Female
MQDEC-403SS	0.91 m (3 ft)			<u></u>
MQDEC-406SS	1.83 m (6 ft)		40 Typ	1-
MQDEC-412SS	3.66 m (12 ft)		[1.58"]	4
MQDEC-420SS	6.10 m (20 ft)		M12 x 1	Male
MQDEC-430SS	9.14 m (30 ft)		ø 14.5 [0.57"]	ividio
MQDEC-450SS	15.2 m (50 ft)		44 Typ. [1.73"]  M12 x 1  ø 14.5 [0.57"]	31
				1 = Brown 2 = White 3 = Blue 4 = Black

4-Pin Threaded M12/Euro-Style Cordsets—Double Ended, Oil Resistant				
Model	Length	Style	Dimensions	Pinout
MQDEC-401SS-PUR	0.3 m (1 ft)			Female
MQDEC-403SS-PUR	1 m (3.28 ft)			2
MQDEC-406SS-PUR	2 m (6.56 ft)		40 Typ. [1.58"]	1-
MQDEC-415SS-PUR	5 m (16.40 ft)			4-3
MQDEC-430SS-PUR	10 m (32.81 ft)	Male Straight/ Female Straight	M12 x 1	Male  2  4  1 = Brown 2 = White
				3 = Blue 4 = Black

4-Pin Threaded M12/Euro-Style Cordsets—Double Ended, Washdown, Stainless Steel				
Model	Length	Style	Dimensions	Pinout
MQDEC-WDSS-401SS	0.3 m (1 ft)			Female
MQDEC-WDSS-403SS	0.91 m (3 ft)			2
MQDEC-WDSS-406SS	1.83 m (6 ft)		40 Typ. ———	1-
MQDEC-WDSS-412SS	3.66 m (12 ft)	Male Straight/ Female Straight	M12 x 1 13.9 13.9 13.9 1	Male  1  1 = Brown 2 = White 3 = Blue 4 = Black

### 8.2 Brackets

All measurements are listed in millimeters, unless noted otherwise.

#### SMBQ4X..

- Swivel bracket with tilt and pan movement for precision adjustment
- Easy sensor mounting to extruded rail T-slots
- Metric and inch size bolts available
- Side mounting of some sensors with the 3 mm screws included with the sensor



#### $B = 7 \times M3 \times 0.5$

Model	Bolt Thread (A)
SMBQ4XFA	3/8 - 16 × 2¼ in
SMBQ4XFAM10	M10 - 1.5 × 50
SMBQ4XFAM12	n/a; no bolt included. Mounts directly to 12 mm (½ in) rods

#### SMB18FA..

- Swivel bracket with tilt and pan movement for precision adjustment
- Easy sensor mounting to extruded rail T-slots
- Metric and inch size bolts available
- 18 mm sensor mounting hole

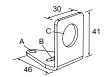
Hole size: B=ø 18.1

Model	Bolt Thread (A)
SMB18FA	3/8 - 16 × 2 in
SMB18FAM10	M10 - 1.5 × 50
SMB18FAM12	n/a; no bolt included. Mounts directly to 12 mm (½ in) rods

#### SMB18A

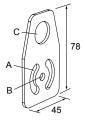
- Right-angle mounting bracket with a curved slot for versatile orientation
- 12-ga. stainless steel
- 18 mm sensor mounting hole
- Clearance for M4 (#8) hardware

Hole center spacing: A to B = 24.2 Hole size: A =  $\emptyset$  4.6, B = 17.0 × 4.6, C =  $\emptyset$  18.5



#### SMBAMS18P

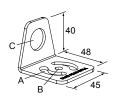
- Flat SMBAMS series bracket with 18 mm hole
- Articulation slots for 90+° rotation
- 12-ga. (2.6 mm) coldrolled steel



Hole center spacing: A = 26.0, A to B = 13.0 Hole size: A =  $26.8 \times 7.0$ , B =  $\emptyset$  6.5, C =  $\emptyset$  19.0

#### SMBAMS18RA

- Right-angle SMBAMS series bracket with 18 mm hole
- Articulation slots for 90+° rotation
- 12-ga. (2.6 mm) coldrolled steel



Hole center spacing: A = 26.0, A to B = 13.0Hole size:  $A = 26.8 \times 7.0$ ,  $B = \emptyset 6.5$ ,  $C = \emptyset 19.0$ 

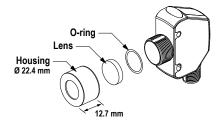
## 8.3 Aperture Kits—Threaded Barrel Models

#### APG18S

Kit with glass lens to protect plastic sensor lens from chemical environments and weld splatter damage.



Used with S18, M18, T18, TM18, and Q4X



#### Additional Information

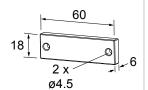
- Borosilicate glass window protects the PMMA window from weld splatter and chemicals
- Adds 4.8 mm to the length of the threaded barrel
- Reduces excess gain by 30%; increase the response time to restore excess gain

### 8.4 Reference Targets

All measurements are listed in millimeters, unless noted otherwise.

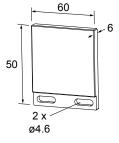
#### BRT-Q4X-60X18

- Reference target for clear object detection or dual mode applications
- FDA grade acetal material



#### BRT-Q4X-60X50

- Reference target for clear object detection or dual mode applications
- FDA grade acetal material



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