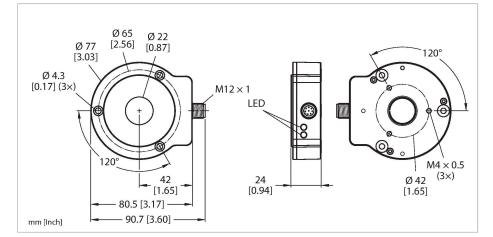


RI360P0-EQR24M0-INCRX2-H1181 Contactless Encoder with Stainless Steel Housing – Incremental: 1 ... 5000 ppr Premium Line





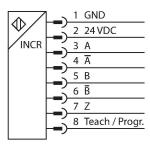
Technical data

Туре	RI360P0-EQR24M0-INCRX2-H1181
ID	1590912
Measuring principle	Inductive
General data	
Max. rotational speed	10,000 rpm
	Determined with standardized construc- tion, with a steel shaft \emptyset 20 mm, L = 50 mm and reducer \emptyset 20 mm.
Starting torque shaft load (radial / axial)	not applicable, because of contactless measuring principle
Nominal distance	1.5 mm
Repeat accuracy	≤ 0.01 % of full scale
Linearity deviation	≤ 0.05 % f.s.
Temperature drift	≤ ± 0.003 %/K
Output type	Incremental
Resolution incremental	1024 ppr
Electrical data	
Operating voltage $U_{\scriptscriptstyle B}$	1030 VDC
Ripple U _{ss}	≤ 10 % U _{Bmax}
Isolation test voltage	0.5 kV
Short-circuit protection	yes/Cyclic
Wire break/reverse polarity protection	yes/yes (voltage supply)
Pulse frequency max.	200 kHz
Signal level high	min. U _B - 2 V
Signal level low	max. 2.0 V
Output function	8-pin, Push-Pull/HTL

Features

- Compact, rugged housing
- Active face, plastic PA12-GF30
- Housing, stainless steel V4A (1.4404)
- Status displayed via LED
- Immune to electromagnetic interference
- 1024 pulses per revolution (default)
- 360, 512, 1000, 1024, 2048, 2500, 3600, 4096, parametr. via Easy-Teach
- Free parametrization of the pulse number in the range from 1 to 5000 via PACTware™
- Position of z-track set via Easy-Teach
- Burst function, absolute angular position output incrementally per Easy-Teach pulse
- 10...30 VDC
- Male M12 x 1, 8-pinPush-pull A, B, Z, A (inverse), B (inverse)

Wiring diagram





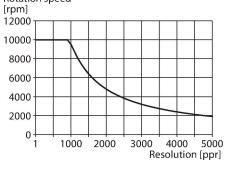


Technical data

Sample rate	1000 Hz
Current consumption	< 100 mA
Mechanical data	
Design	EQR24
Dimensions	81 x 78 x 24 mm
Flange type	Flange without mounting element
Shaft Type	Hollow shaft
Shaft diameter D (mm)	6 6.35 9.525 10 12 12.7 14 15.875 19.05 20
Housing material	Stainless-steel/Plastic, 1.4404 (AISI 316L)/PA12-GF30
Electrical connection	Connector, M12 × 1
Environmental conditions	
Ambient temperature	-25+85 °C
	Acc. to UL approval to +70 °C
Vibration resistance	55 Hz (1 mm)
Vibration resistance (EN 60068-2-6)	20 g; 103000 Hz; 50 cycles; 3 axes
Shock resistance (EN 60068-2-27)	100 g; 11 ms ½ sine; 3 × each; 3 axes
Continuous shock resistance (EN 60068-2-29)	40 g; 6 ms ½ sine; 4000 × each; 3 axes
Protection class	IP68 IP69K
MTTF	138 years acc. to SN 29500 (Ed. 99) 40 °C
Power-on indication	LED, Green
Measuring range display	LED, yellow, yellow flashing
Included in delivery	Adapter sleeve MT-QR24
UL certificate	E210608

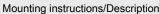
Functional principle

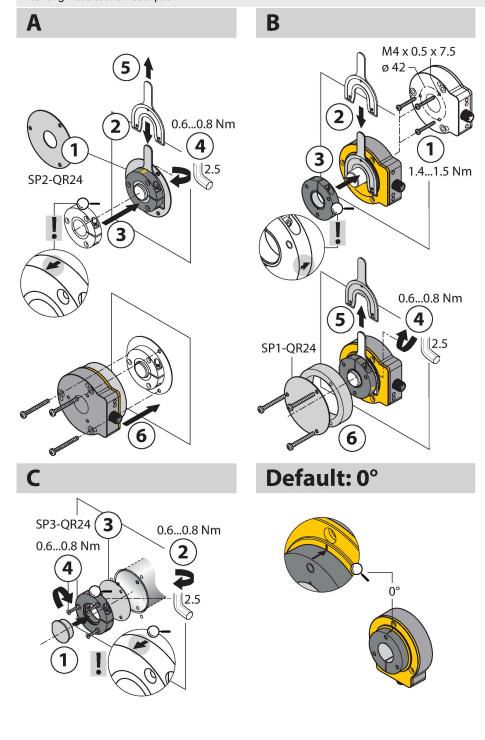
The measuring principle of inductive angle sensors is based on oscillation circuit coupling between the positioning element and the sensor, whereby an output signal is provided proportional to the angle of the positioning element. The rugged sensors are wear and maintenance-free, thanks to the contactless operating principle. They convince through their excellent repeatability, resolution and linearity within a broad temperature range. The innovative technology ensures a high immunity to electromagnetic DC and AC fields. Rotation speed





Mounting instructions





The extensive range of mounting accessories enables easy adaptation to many different shaft diameters. Due to the measuring principle, which is based on the functional principle of an RLC coupling, the encoder is immune to magnetized ferrous chips and other interferences. As a result, there are few possible causes of error during mounting. The adjacent figures show the simple installation of the two separate units: the sensor element and the positioning element: Mounting option A:

First, connect the positioning element to the rotatable shaft using the bracket. Then place the encoder with the aluminum ring above the rotating part in such a way that you get a closed and protected unit. Mounting option B:

Slide the encoder backward onto the shaft and fasten it to the machine. Then fasten the positioning element to the shaft using the bracket.

Mounting option C:

If the positioning element is screwed onto a rotating machine part rather than being put on a shaft, you must first insert the dummy plug RA8-QR24. Then tighten the bracket. Next, mount the encoder via the three bores.

Due to the separate installation of positioning element and sensor, no electrical currents or harmful mechanical forces are transmitted to the sensor via the shaft. The encoder also offers a high degree of protection throughout its service life and stays permanently sealed. During commissioning, the accessories included in the delivery help to mount the encoder and the positioning element at an optimal distance from each other. In addition, LEDs indicate the status. Optionally, you can use the shield plates included in the accessories to increase the permitted distance between the positioning element and the sensor.

Status display via LED Green: Sensor is being supplied properly Yellow: Positioning element is within the measuring range, low signal quality (e.g. distance too great) Yellow flashing:

Positioning element is outside the detection range

Off: Positioning element is within the measuring range

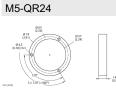
Individual Parameterization	(Teaching with Positioning	g Element)		
Jumper between teach	Gnd Pin 1	Ub Pin 2		LED
input Pin 8				
2 s	Z-track zero point	One-time triggering of burst		Status LED flashes then
	teaching	function		turns steady after 2 s
10 s	CCW rotation	CW rotation direction After 10 s status LED		After 10 s status LED
	direction	flashes fast for 2		flashes fast for 2 s
15 s	-	Factory setting (z-track, CW) After 15 s power an		After 15 s power and
				status LED alternate
To avoid unintended teaching				
Preset Programming Mode		, ,		
Jumper between teach	Gnd Pin 1	Ub Pin 2 LED		
input Pin 8				
	2 s	2 s		LED steady, flashes after
	Resolution setting	Resolution setting		ong as selection mode is
	mode active for 10 s	mode active for 10 s	active	
360 pulses/360°	Start value		1 x flas	hing
512 pulses/360°	Press once		2 x flashing	
1000 pulses/360°	Press twice		3 x flashing	
1024 pulses/360°	Press three times		4 x flashing	
2048 pulses/360°	Press four times		5 x flashing	
2500 pulses/360°		Start value	1 x flashing	
3600 pulses/360°		Press once	2 x flashing	
4096 pulses/360°		Press twice	3 x flashing	
5000 pulses/360°		Press three times	ree times 4 x flashing	
To avoid unintended teaching	ng, keep pin 8 potential-fre	96.		

Accessories





1590966 Positioning element with stainless steel compression fitting, without adapter sleeve



1590965

Plastic protecting ring for encoders RI-EQR24

RA1-EQR24

1593019 Stainless steel adapter sleeve, for Ø 20 mm shafts

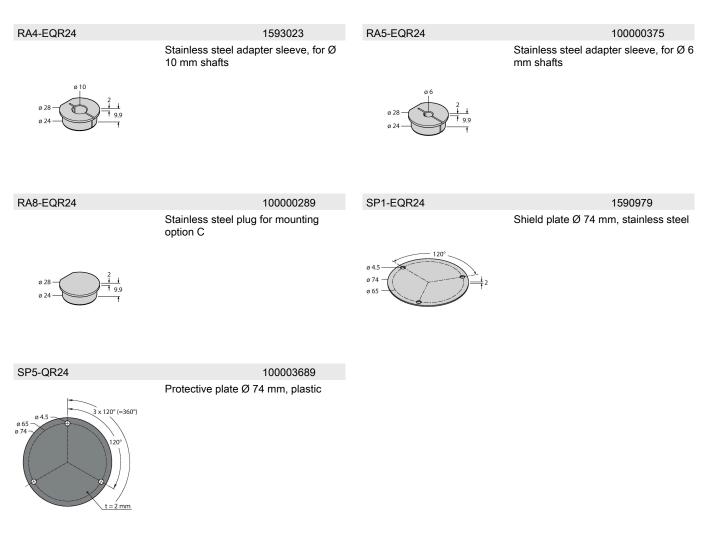
RA3-EQR24

1593020

Stainless steel adapter sleeve, for Ø 12 mm shafts







Accessories

Dimension drawing	Туре	ID	
	RKCV8T-2/TFW	6934668	Connection cable, M12 female connector, straight, 8-pin, stainless steel coupling nut, cable length: 2 m, jacket material: PP-EPDM, white
M12x1 015 2 14	RKC8T-2/TXL	6625142	Connection cable, M12 female connector, straight, 8-pin, cable length: 2 m, jacket material: PUR, black; cULus approval
M12x1 015 514 + 115 + + 182 + 49.5 + 182 +	RKC8.302T-1.5-RSC4T/TXL320	6625003	Adapter cable to connect sensor to USB-2-IOL-0002 programming unit; M12 female connector, straight, 8-pin to M12 male connector, straight, 3-pin; cable length: 1.5 m; jacket material: PUR, black; cULus approved; RoHS compliant; protection class IP67



Accessories

